

ECE 471 – Embedded Systems

Lecture 30

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Announcements

- HW#11 was posted
- Feel free to return borrowed hardware.



Ethernet

- Old, complicated standard, whole way up to 100GBps
- Modern form is often RJ-45, twisted pairs
- Power over ethernet (only Pi3B+ support)
- PiB models have 10/100 Mbps, Pi3B+ has “gigabit”
- Connected to on-board USB hub



HDMI

- High-Definition Multimedia Interface (2003)
- Compatible with DVI (if no copy protection used)
- Video, audio (up to 8 channels), CEC (consumer electronics control), ethernet
- No support for captions
- DDC – i2c bus, used for EDID (getting device info) and HDCP (copy protection)



- TDMS – transition minimized differential signaling
Video, then during scan line breaks, audio, etc
- CEC – control up to 15 devices with one remote control
(one wire serial bus)
- Various versions, various fees



Other video ports

- NTSC/composite – Pi has (hidden on later models)
- VGA (analog) – hard to get on Pi
- DSI connector – for touchscreen
- DVI
- Thunderbolt
- Displayport



- USB?



Other Busses not found until RPI-3



Wireless / Wifi

- Wireless ethernet
- 2.4GHz or 5GHz



Bluetooth

- Basic unit: piconet, master node and up to seven *active* slave nodes within 10m
- Many can exist in an area, and can be connected by a bridge. Connected piconets are called a scatternet
- There can also be up to 255 “parked” nodes in a picnoet
- When parked, can only respond to activation on beacon
- Hold and siff?
- Slaves designed to be cheap, so dumb. Master is smart and runs them. slave/slave communication not possible



- Master broadcasts clock 312.5us. Master transmits in even, slave in odd.
- Radio layer – 2.4GHz, 10 meters. 79 channels of 1MHz.
- pairing
- Bluetooth V1.1 has 13 different application protocols.
- Bluetooth 4.0 (Bluetooth Low Energy) (2010)
 - 25Mbps/200 feet
 - Entirely new stack, designed for low power rapid setup links
 - Not backwards compatible, but same frequency range
 - New profiles



- Linux interface: depends on type. Filetransfer/obex.
Audio (looks like an audio driver) network device, serial device



Bluetooth and Linux

- Two competing stacks, BlueZ and Affix

```
sudo bluetoothctl
```

```
[sudo] password for vince:
```

```
[NEW] Controller B8:27:EB:52:DD:E8 linpack-test
```

```
[bluetooth]# power on
```

```
Changing power on succeeded
```

```
[bluetooth]# scan on
```

```
Discovery started
```

```
[CHG] Controller B8:27:EB:52:DD:E8 Discovering:
```



```
[NEW] Device AC:37:43:89:4C:02 HTC BS 02CA47
```

```
[NEW] Device AC:37:43:89:2F:86 HTC BS 86B06E
```

```
[CHG] Device AC:37:43:89:2F:86 RSSI: -90
```

```
[bluetooth]# scan on
```

```
Failed to start discovery: org.bluez.Error.InPr
```

```
[bluetooth]# connect AC:37:43:89:4C:02
```

- obexpushd. Appears as serial port?



CANbus

- Automotive. Introduced by BOSCH, 1983
- One of OBD-II protocols
- differential, 2 wires, 1MBps important things like engine control
- single wire, slower cheaper, hvac, radio, airbags



CANbus Protocol

- id, length code, up to 8 bytes of data id (usually 11 or 29 bits) type and who is sending it. Also priority (lower is higher) length is 4 bits. some always send 8 and pad with zeros
- Type is inferred from id. Can be things like engine RPM, etc
- DBC database has the ids and values. ASCII text database, hard to get legally.



- Dominant/Recessive. Message with lowest ID wins arbitration.
- CAN-FD – extended version with larger sizes



CANbus Linux

- Can4linux – `open("/dev/can0"); read(); write();`
External project?
- SocketCAN – contributed by Volkswagen. In kernel.
Uses socket interface. `/Documentation/networking/can.txt`



CANbus on Pi

- Not by default
- Can get SPI to CANbus adapters



ISA Bus

- Introduced with IBM-PC in 1981
- 8-bit (4.77MHz) then 16-bit (8MHz)
- +/-5V, +/-12V, 8 data, 20 address, DMA, IRQ
- Replaced by VLB (more pins, extra header), EISA (double pins in same connector), MCA micro-channel (different proprietary from IBM)



- Not enumerable at first, set jumpers. Later “Plug-n-Play”



LPC Bus

- Low-pin-count bus
- Intel, 1998, try to get rid of ISA
- Things like PS/2, Serial ports, floppy, etc.
Still used for TPM Trusted Computing nonsense
- Replace 16-bit 8.33MHz parallel bus with 4-bit wide 33.3MHz bus. Only 7 wires. Easier to route than 72



“Conventional” PCI Bus

- Peripheral Component Interconnect
- Enumerable
- 1993, intel
- 62-pins, parallel, 133MB/s
- Extended with 32 or 64-bit versions, 33 or 66MHz, 3.3 or 5V. All slight differences in connectors to support all that.



- AGP (Accelerated Graphics Card) for graphics cards. 1997. Direct connect to CPU (not shared), multiple channels, faster clock
- PCI-X 1998, extension to 133MHz. Not to be confused with PCI-Express (PCIe)



PCI protocol

- 256B Config space, mapped into CPU address. Small area system can probe, used to setup larger mappings
- Can have on-board ROM that can be executed. Problem when using on non-x86 systems (emulators needed? special [expensive] PowerPC versions?)
- Latency timers keep bus-master from hogging bus
- 4 interrupt lines, can be shared. Level rather than edge-triggered interrupts make sharing easier





PCIe

- PCI-express, 2003
- Serial, replaced point-to-point with lanes, packet-based
x1, x2, x4, x8 x16, x32
- Compatible with PCI at software level
- Differential Signaling
- External – Thunderbolt



- Serial better due to timing skew
- New x86 audrino quark has PCIe



PCleexpress Mini

- PCIe x1, USB, SMBus, etc
- Smaller card



PCMCIA Bus

- Personal Computer Memory Control International Association
- 16-bit
- Cardbus, 32-bit
- Mostly replaced these days



PC/104 Bus

- Stackable small x86 boards usually
- Run ISA or PCI signals up vertically



VME Bus

- m68k bus but generic enough
- Still found in some embedded systems



Other

- SATA, eSATA, PATA, SCSI (disk drives)
- Firewire
- RapidIO
- Quickpath QPI
- Hypertransport
- Thunderbolt (requested)



- List of competing busses at end of USB wiki article

