ECE 574 – Cluster Computing
Lecture 7

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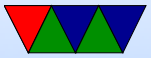
Announcements

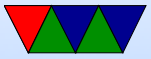
- Homework #3 was posted. Don't put it off until the last minute!
- Lots of coding
- Later homeworks will build off of it, but don't worry I will provide solutions
- Behind on grading due to large number of faculty zoom interviews as well as lovebyte deadline



Homework #3 Notes

- You can output intermediate sobel results for debugging
- If almost right except for a few areas, most likely forgot to saturate

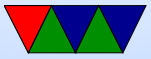
  note you need to saturate after combine as well
- If you run into trouble, send me your code to look at
- PAPI: be sure to do things in right order
- PAPI: if get weird results, be sure to check error returns from the functions. There's a `PAPI_sterror()` that can help



Homework #2 Review – Measurements

Procs	1	2	4	8	16	32	64
Time	115	59	33	19	15	16	16
GFLOPS	46	90	162	2275	365	328	331
Speedup	—	1.95	3.48	6.05	7.67	7.19	7.19
Peff	—	0.98	0.87	0.76	0.48	0.22	0.11

- 3bi) Speedup: (t1/tp)
  This year moving to 32 threads actually helped slightly
  What is different? Kernel? Compiler? OpenBLAS? Firmware?
- 3bii) Parallel efficiency: (Sp/p or T1/pTp)
- 3biii) Yes, time decreases as you add cores.

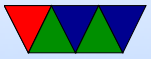


Not ideal strong scaling though.

Note: “weak” is not the same as “poor strong scaling”

- 3biv) No weak, didn't test with sizes constant

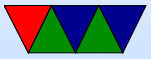
  How could we test this?
- 3bv Time is less as only dgemm, not malloc or randomizing
- 3bvi More because user adds up all threads/cores



Homework #2 Review – perf record

- 3a) dgemm kernel (double-precision generic matrix-matrix multiply. algorithm kernel (core) not Linux kernel) If you got big time in kernel, you ran perf on time

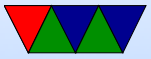
```
46.34%  xhpl     xhpl                  [.] dgemm_kernel
14.95%  xhpl     [kernel.kallsyms]     [k] syscall_exit_to_user_mode
 5.30%  xhpl     [kernel.kallsyms]     [k] entry_SYSCALL_64
 4.82%  xhpl     [kernel.kallsyms]     [k] syscall_return_via_sysret
 2.95%  xhpl     xhpl                  [.] HPL_lmul
 1.68%  xhpl     [kernel.kallsyms]     [k] update_curr
 1.62%  xhpl     [kernel.kallsyms]     [k] __schedule
 1.47%  xhpl     [kernel.kallsyms]     [k] entry_SYSCALL_64_after_hwframe
 1.26%  xhpl     [kernel.kallsyms]     [k] pick_next_task_fair
 1.13%  xhpl     [kernel.kallsyms]     [k] __calc_delta.constprop.0
 1.08%  xhpl     xhpl                  [.] HPL_rand
```



Homework #2 Review – perf annotate

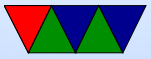
```
0.32 :        vbroadcastsd -0x60(%rdi),%ymm0
0.24 :        vfmadd231pd  %ymm0,%ymm1,%ymm4
0.28 :        vfmadd231pd  %ymm0,%ymm2,%ymm8
0.27 :        vfmadd231pd  %ymm0,%ymm3,%ymm12
0.21 :        vbroadcastsd -0x58(%rdi),%ymm0
0.44 :        vfmadd231pd  %ymm0,%ymm1,%ymm5
0.19 :        vfmadd231pd  %ymm0,%ymm2,%ymm9
0.37 :        vfmadd231pd  %ymm0,%ymm3,%ymm13
0.09 :        vbroadcastsd -0x50(%rdi),%ymm0
```

- in dgemm_kernel()
  vbroadcastd – broadcast 64-bit fp value from memory and copy 4 times in 256-bit AVXregister



vfmadd231pd – fused multiply-add of packed doubles. 231 refers to the order of the operands (2*3+1, store in 1)

- 3c) skid
  - Will :pp avoid the skid?
  - Why no one thing stand out in profile?
    Hand optimized assembly, people have worked a long time on optimizing this getting low hanging stuff
  - Both instructions only listed as latency 1 in the agner fogg, though that doesn't count cache access

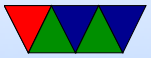


Homework #2 – Weak Scaling Info

If ideal strong scaling, then parallel efficiency would be closer to 1. Not enough results for weak scaling.

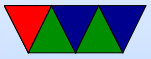
To get 1G/core, roughly $\frac{2}{3} * n^3 = 500B * p$

Cores		N=20k	Size=3.2G	Size=1G/core	time	Speedup	GFLOPs
1	119s	3.2G	11,000	9000	11.5	—-	42.5
2	64s	1.6G	16,000	11500	14	0.82	72
4	37s	0.8G	22,360	14400	14	0.82	139
8	22s	0.4G	31,600	18200	18	0.63	222
16	18s	0.2G	44,700	22900	26	0.44	304
32	18s	0.1G	63,240	28800	47	0.24	336
64	18s	0.05G	89,000	36000	93	0.12	334

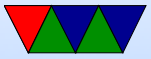


From Last time

- Go over NUMA briefly
- Go over Shared Memory vs Distributed Briefly

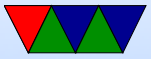


Parallel Programming!



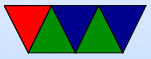
Single-Thread Processes

- A process is a program running on a computer, usually being managed by an operating system
- Process has one view of memory, one program counter, one set of registers, one stack



Multi-tasking / Multi-Programming

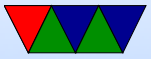
- Most OSes give illusion of running multiple processes at once (even on a single core system)
- Rapidly switch between all running processes, hundreds of times a second
- Context switch – each process has own program counter saved and restored as well as other state (registers)
- Virtual Memory is used to give each process illusion they have sole access to memory in the machine
- OSes often have many things running, often in



background.

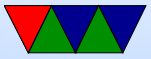
On Linux/UNIX sometimes called daemons

Can use `top` or `ps` to view them.



Processes: OS Interface

- Creating new: on Unix its fork/exec, windows CreateProcess
- Children live in different address space, even though it is a copy of parent
- Process termination: what happens?
  Resources cleaned up. `atexit()` routines run.
  How does it happen?
  `exit()` syscall (or return from main).
  Killed by a signal.

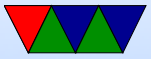


Error

- Unix process hierarchy.

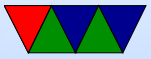
  Parents can wait for children to finish, find out what happened

  not strictly possible to give your children away, although init inherits orphans
- Process control block.

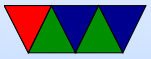


Could you build a multi-cpu program using just Processes?

- Yes
- Need to pass data between the different processes
- Network – use sockets (network on UNIX domain sockets)
  Message Passing
- Shared Memory – interfaces like SYSV Shared Memory or mmap() could create memory region shared by two processes

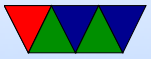


- This is a pain to code for, ways to automate?

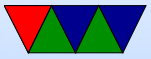


Threads

- Default: each process has one address space and single thread of control.
- It might be useful to have multiple threads share one address space
  - GUI: interface thread and worker thread?
  - Game: music thread, AI thread, display thread?
  - Webserver: can handle incoming connections then pass serving to worker threads
  - Why not just have one process that periodically

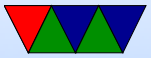


switches?

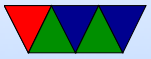


Multithreading

- Implementation:
  Each thread has its own PC
  Each thread has its own stack
- Why do it?
  shared variables, faster communication
  multiprocessors?
  mostly if does I/O that blocks, rest of threads can keep going
  allows overlapping compute and I/O

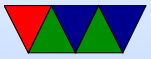


- Problems:
  What if both wait on same resource (both do a scanf from the keyboard?)
  On fork, do all threads get copied?
  What if thread closes file while another reading it?



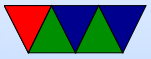
Thread Implementations

- Cause of many flamewars over the years



User-Level Threads (N:1 one process many threads)

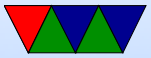
- Benefits
  - Kernel knows nothing about them. Can be implemented even if kernel has no support.
  - Each process has a thread table
  - When it sees it will block, it switches threads/PC in user space
  - Different from processes? When thread_yield() called it can switch without calling into the kernel (no slow



kernel context switch)
  - Can have own custom scheduling algorithm
  - Scale better, do not cause kernel structures to grow

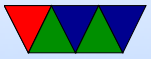
- Downsides
  - How to handle blocking? Can wrap things, but not easy. Also can't wrap a pagefault.
  - Co-operative, threads won't stop unless voluntarily give up.

    Can request periodic signal, but too high a rate is inefficient.

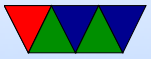


Kernel-Level Threads (1:1 process to thread)

- Benefits
  - Kernel tracks all threads in system
  - Handle blocking better
- Downsides
  - Thread control functions are syscalls
  - When yielding, might yield to another process rather than a thread

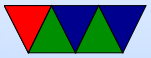


– Might be slower



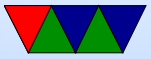
Hybrid (M:N)

- Can have kernel threads with user on top of it.
- Fast context switching, but can have odd problems like priority inversion.



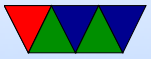
What about co-routines

- Not found in C
- Sort of like co-operatively scheduled software threads
- functions can be suspended at various points and re-started later
- Less issues than full threads as only one can run at a time, simplifying locking



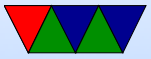
POSIX Threads (pthreads)

- Standardized thread interface
- Standard cross-platform set of routines to use



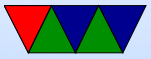
Linux Threading – Historical

- Linux original thread implementation was horrible software based
- Originally used only userspace implementations. GNU portable threads.
- LinuxThreads – use clone syscall, SIGUSR1 SIGUSR2 for communicating.
  Could not implement full POSIX threads, especially with signals. Replaced by NPTL
  Hard thread-local storage



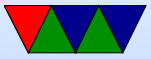
Needed extra helper thread to handle signals

Problems, what happens if helper thread killed? Signals broken? 8192 thread limit? proc/top clutter up with processed, not clear they are subthreads



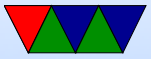
Linux Threading – NPTL

- NPTL – Native POSIX Thread Library
- Kernel threads
- Clone syscall, new futex system calls.
- Developed around 2003 or so by Drepper and Molnar at RedHat, Kernel 2.6
- Why kernel? Linux has very fast context switch compared to some OSes.
- Need new C library/ABI to handle location of thread-local storage



On x86 the fs/gs segment used. Others need spare register.

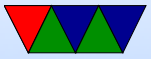
- Signal handling in kernel
- Clone handles setting TID (thread ID)
- exit_group() syscall added that ends all threads in process, exit() just ends thread.
  exec() kills all threads before execing
  Only main thread gets entry in proc



Pthread Programming

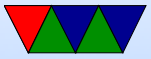
- based on this really good tutorial here:

  `https://hpc-tutorials.llnl.gov/posix/`



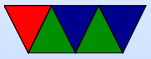
Pthread Programming

- Changes to shared system resources affect all threads in a process (such as closing a file)
- Identical pointers point to same data
- Reading and writing to same memory is possible simultaneously (with unknown origin) so locking must be used



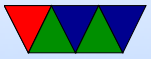
When can you use?

- Work on data that can be split among multiple tasks
- Work that blocks on I/O
- Work that has to handle asynchronous events



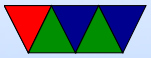
Models

- Pipeline – task broken into a set of subtasks that each execute serial on own thread
- Manager/worker – a manager thread assigns work to a set of worker threads. Also manager usually handles I/O static worker pool – constant number of threads dynamic worker pool – threads started and stopped as needed
- Peer – like manager/worker but the manager also does calculations



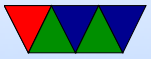
Shared Memory Model

- All threads have access to shared memory
- Threads also have private data
- Programmers must properly protect shared data



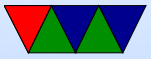
Thread Safety

- Is a function called thread safe?
- Can the code be executed multiple times simultaneously?
- The main problem is if there is global state that must be remembered between calls. For example, the strtok() function.
- As long as only local variables (on stack) usually not an issue. (avoid globals)
  Can be addressed with locking.

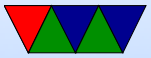


POSIX Threads

- 1995 standard
- Various interfaces:
  1. Thread management: Routines for manipulating threads – creating, detaching, joining, etc. Also for setting thread attributes.
  2. Mutexes: (mutual exclusion) – Routines for creating mutex locks.
  3. Condition variables – allow having threads wait on a lock



4. Synchronization: lock and barrier management



POSIX Threads (pthreads)

- A C interface. There are wrappers for Fortran.
- Over 100 functions, all starting with pthread_
- Involve "opaque" data structures that are passed around.
- Include pthread.h header
- Include -pthread in linker command to compiler