

ECE 271 – Microcomputer Architecture and Applications Lecture 3

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Announcements

- Read Chapter #1 of the book.
- Labs have started! Don't forget to do the pre-lab
- The course website should be visible to the outside world again.



Lab Update

- Notes on how the labs work:
 - Do the pre-lab before coming to lab.
This will be checked off by the TA at the start of the lab.
I will try to post prelab by Thursday
 - Do lab during lab time.
 - Be sure to comment your code! Also put a header at the top of your code with your name, date, class, and a short summary of what the code does.



- Once you have completed the lab, demo it to the TA. You will turn in the code (eventually via git).
- There will be a post-lab with a few questions. Answer these in the README file (or maybe README.md) and include that with your assignment code.



Lab Grading Rubric

- prelab 2-points: show up for lab, complete pre-lab
- document 5-points: comment code, readme, header, git commits, C style
- functional code 5-points: code works, no warnings or errors (or at least no relevant warnings)
- lab demonstration 5-points: demo it, plus post-lab
- something cool 3-points



Operating Systems for the labs

- By default just use Keil on Windows
- If you are feeling adventuresome I also posted templates for Linux which you can find on the webpage
- If you are using MacOSX you have a few options. You can try using the Linux files via homebrew. Or you can dual-boot your machine into Windows, or run Windows in a VM.

All of these are sort of advanced and neither the TAs nor I can necessarily be much help if it goes wrong.



Review Masking

- The prelab has you calculate some values in advance, so you don't have to waste valuable lab time doing it
- You need to set certain bits to a value without changing the surrounding existing bits
- Recall that bitwise OR with 0 leaves the bit a same, OR with 1 sets it to 1. Bitwise AND with 0 clears a bit, AND with 1 leaves the same.
- So what you want to do is first MASK off the value using AND, then you can OR the value in (0 or 1) and



it will get set

- The term MASK is used because you are protecting the other bits from being changed, sort of how you might use a paper mask with an opening in it when painting.



Setting the Right Values

- The hardest thing about this lab is setting the right values
- Embedded systems like this are super unforgiving
- One bit wrong and nothing will work at all
- Double check your values
- How can you tell if the hardware has the right value?



Debugging!

- How do you find out what your code is doing?
- `printf()`, but can we do that on this board?
- Use a debugger!
- Embedded boards support remote debugging, where you can control the processor execution from another machine.
- Keil debugger. `gdb` is common on Linux



Debuggers

- Set breakpoints to stop when code hits a certain point
- Single-step through code (or assembly language)
- View register state, variable values
- Can view the hardware registers to be sure they're being loaded with proper values



Commenting your Code

- Comment your code!
- 6 months out could someone else understand your code?
- 6 months out can **you** still understand your code?



Useful Code Comments

- How to comment. Which is more useful?

```
i=2; /* set i equal to 2 */  
i=2; /* set i to the LED to enable */
```



git

- SCM – source code management
- Digression on how Linus invented it
CVS not an option
bitkeeper + LM
Never make Linus mad
- How it works. Never ask. Lots of hashes and lines and diagrams. xkcd comic?



git actions

- Can have GUI or command line
- `git init` creates repository
- `git clone` clones an existing repository
- `git pull` make files up to date
- `git add` queue changes in file to repository
- `git commit` add queued changes to repository
- `git push` push changes to remote repository



SCM concepts

- Good commit messages
 - Not just "blah" or "fixed bug" or "asdfghj" or "I hate coding"
 - Linux have detailed first line, then often pages of explanation
 - Maybe not need that for this class.
 - Should help someone auditing/maintaining code understand what code change is doing.
- Push out to server if you have one (github, gitlab, etc)



- Benefits:
 - Can roll back to former version of code
 - When pushed out to other locations full backup
 - Can work together (though watch for merge)
 - git bisect
 - Try to find out why a change was made (git blame), hope for good commit message.
- hashes: cryptographic hash (string of hex numbers) used to track changes. Will often see these referenced for changesets.



Bare Metal vs Operating System



Running code w/ Operating System

- At boot, firmware runs, runs boot loader, this loads Operating System, eventually starts some sort of launcher (shell) that lets you run programs
- Device drivers abstract away talking to hardware
- Program talks to the operating system via “system calls”
- Program is an “executable”, which has machine code and data. O/S along with loader/linker will take program, copy to memory, set up registers/stack, then jump to code.



- Draw memory map (Virtual Memory is involved but beyond scope of class)
- When program done, exits, which returns control to Operating System



Running code on Bare Metal

- Code loaded into flash
- Power on, start with nothing. Have to do things like enable clocks.
- No device drivers, if want to talk to hardware have to flip bits in config registers manually
- Executable is just a blob, any writable data you have has to be copied to SRAM
- Can't exit your code. If you don't stop execution with a loop you'll run off the end and try to interpret



uninitialized RAM as instructions.



Helper Code in the Template

- There's some code that turns on the 80MHz clock to the whole chip
- There's a linker script which tells the compiler how to set up the code for the flash-image to be burned
- The beginning of the flash image is the initial stack-pointer value, which loads into the stack pointer (SP) at boot.

What should this point to? (The **end** of memory, stacks grown down).



- The next set of 32-bit values in the image are interrupt vectors. One of them is the reset vector; that address is jumped to at reset time. The provided code points this to your `main()` function.



CPU clocks

- A modern CPU has lots of clocks going on
- We have code that turns on the main 80MHz clock
- There's a diagram in the manual showing all the various speeds and sub-clocks you can enable.
- On a desktop/laptop/phone someone does this for you, but here on bare-metal we have to worry about it.



Switch Debouncing

- What is it
- Why needed
- Hardware
- Software

