

# **ECE 271 – Microcomputer Architecture and Applications Lecture 10**

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# Announcements

- Read Chapter 2, Chapter 16
- Please have the prelab done by the beginning of the lab section
- The TA is handling deadlines for the labs so check with him first if you have questions about those. If you have concerns about his decisions then feel free to bring them up with me.



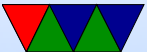
# The Debugger / Debugging

- Debuggers let you track program behavior while code is running. Often the best way to find/fix problems in your code.
- Alternatives:
  - Code inspection – even the best programmers can struggle at that
  - Lots of `printf()`s – not really practical on embedded system



# Keil Tools

- Is it the best debugging environment ever?  
No, but it's not the worst either
- As an aside, why does Keil give away their tools for "free"?



# How does it work?

- A bit hardware dependent
- Usually a mechanism that allows halting running system and reading out all of the hardware state (most importantly the program counter, stack, registers, and memory contents)



# Setting breakpoints

- Set a location in code where you want execution to stop
- Maybe you want to stop after you've done initialization so you can check the register contents match what they should be



# More info on the Program Counter

```
8000010    4990    ldr r1,[pc,#256]
8000012    6ccb    ldr r3,[r1,#76]
8000014    f043
8000016    0302    orr r3,r3,#2
8000018    69c4    str r3,[r1,#76]
...
8000110    40021000 (constant)
```

- PC is at 80000010, so loads the ldr instruction there from memory loads the memory value located at address of  $pc+256$ , stores in r1 instruction done, increments PC to 8000012
- PC is at 80000012, so loads the ldr instruction from memory and decodes loads the memory value located



at address of  $r1+76$ , stores in  $r3$  instruction done, increments (this insn was 2 bytes so to 8000016)

- PC is at 80000106, so loads the orr instruction from memory and decodes orrs the value in  $r3$  with constant #3, stores in  $r3$  instruction done, increments PC to 8000018





# Looking at register contents

- This is when knowing assembly language can be useful



# Setting watchpoints

- Can stop execution if value at a memory address is changed
- Useful if a variable ends up with a value and you have no idea how it's getting that value. Set a watchpoint and hit "run" until the value changes



# Single Stepping

- Once you have a breakpoint near the beginning of where things go wrong, you can single-step through each line of code (or assembly) to make sure the program is executing properly



# Callstack / Stack backtraces

- When you stop, the debugger can look on the stack and show you all functions that were called to get where your code is
- Often it can show you the calling parameters too, though sometimes these get optimized away/over-written so be careful of that



# Processor Exceptions

- If your code does something invalid it can trigger an exception / interrupt that might unexpectedly jump your code to a handler
- Since we have no operating system you won't get notified of this, you'll just find your code stuck at one of the exception handler stubs
- A few that are easier to hit
  - Invalid instruction
  - Invalid memory access



# More ARM/Thumb2 instructions/features

- These aren't needed for the lab, but can be useful to know about
- As always, working code is much more important than clever code



# Conditional Execution

- Note: this is an advanced/obscure technique I am mentioning for completeness, you don't have to know how to use it for this class
- On ARM32 could prefix \*any\* instruction with condition flags, i.e.

```
addeq    r1,r2,r3    ; only does the add if Z=1
addmi    r1,r2,r3    ; only does the add if N=1
```

- On Thumb2 they re-used these encoding bits (the left 4 bits of the instruction) to implement the Thumb-2 set,



so you cannot do this anymore.

- There is a hack called IT, where you can do up to four instructions. The condition has to be the same (Then) or the opposite (Else)

```
itete cc
  addcc r1,r2 @ then
  addcs r1,r2 @ else
  addcc r1,r2 @ then
  addcs r1,r2 @ else
```





# Other Obscure THUMB2 Instructions



# CBZ/CBNZ

- CBZ r0, label
- Special compare-and branch instruction, not change flags
- Can only branch forward



# TBB

- TBB [r0, r1]
- Table-branch byte
- r0 is pointer to table, r1 is offset into table
- Can be used to make switch statements/jump tables



# Saturating Arithmetic

Used in some algorithms, saturate at high or low value rather than wrapping around.

- QADD
- QSUB
- SSAT
- USAT



# Parallel Arithmetic

Can split 32-bit register up into 16 or 8 bit chunks and do arithmetic in parallel (which is faster)

- ADD16
- SUB16
- ADD8
- SUB8
- ASX
- SAX
- USAD8



- USADA8
- SEL (select) – comparisons when doing parallel match can set special multiple-GE (greater/equal) register in the ASPR and bytes can be selected based on this



# Count Leading Zeros

- CLZ – count leading zeros



# Sign/Zero Extension

- SXTB – sign extend a byte
- SXTH – sign extend a halfword
- UXTB – zero extend a byte
- UXTH – zero extend a halfword





# Sign/Zero Extension with add (Cortex-M4/DSP)

- sxtab rd, rn, rm, rotation  
rotate rm right by multiple of 8, extract bottom 7 bits,  
sign extend, add to rn, store in rd
- SXTAB – sign extend a byte
- SXTAB16 –
- SXTAH – sign extend a halfword
- UXTAB – zero extend a byte
- UXTAB16 – zero extend a byte



- UXTAH – zero extend a halfword



# Pack Instruction (Cortex-M4/DSP)

- `pkhbt rd, rn, rm, lsl value`  
combine bits 15:0 of `rn` with bits 31:16 of shifted value from `rm`
- `pkhtb rd, rn, rm, asr value`  
combine bits 31:16 of `rn` with bits 15:0 of shifted value from `rm`
- `PKHTB` – pack halfword top and bottom



# Bitfield

- BFC rd, #lsb, #width – bitfield clear
- BFI rd, rn, #lsb, #width – bitfield insert
- SBFX rd, rn, #lsb, #width – signed bitfield extract
- UBFX rd, rn, #lsb, #width – unsigned bitfield extract



# Bit/Byte Reversing

Useful for handling endianness, network packets, etc.

- RBIT – reverse bit order
- REV – reverse byte order
- REV16 – reverse byte order halfword



# Nop

- nop – no-operation
- Why is this useful?
- Padding code?
- Temporarily commenting out code w/o changing size?
- Delays that do nothing?
- How would you implement this? Are there instructions you can think of that would do nothing? `add r0,r0,#0`?



# Sleep

- What should your device do when not busy?
- Enter a busy infinite loop?
- Wouldn't it be better if you could let the chip know and it could go to sleep / enter low-power mode?
- These do that, and an interrupt (such as a timer or hardware change) can wake the processor and start running code again
  - wfi – wait for interrupt
  - wfe – wait for exception



# System Registers

To configure the processor there are special registers beyond the standard ones. These instructions let you copy values into/out-of these special registers.

- MSR – move from system register
- MRS – move to system register





# System Calls

- SVC
- We don't deal with it in this class, but if you have an operating system you need some way to have your code raise an exception to change security level or let upper layers of software know you need something



# Vector/FP/NEON/DSP

- The Cortex-M4 can handle floating point values
- We will discuss this later in class
- There's a whole separate set of instructions/registers for this



# Non-ARM instructions you might see someday

- branch delay slots
- VLIW (Dsp, GPU, itanium)
- Register windowing
- Really CISC instructions

