

# **ECE 471 – Embedded Systems**

## **Lecture 8**

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# Announcements

- HW#2 was due
- HW#3 will be posted



# Stuff from Last Time

- To shutdown pi, `sudo shutdown -h now`
- The systemd people changed the command line arguments at some point which is why I have trouble remembering
- By default it waits a minute and prints a message to everyone's screen (using the `wall` utility), more useful back in the day when you might have a bunch of people logged into a system



# Coding Style

- How should you format your code?
- Does C have rules? Not really.
- International Obfuscated C Code Competition (IOCCC)  
<https://www.ioccc.org/>
- Your company or open-source project might have strict rules
- In this class as long as your code is relatively easy to follow I am fine with it



# Coding Style – Tabs vs Spaces

- Indent code with a tab character?  
Or 8 spaces (traditional size of a tab)? Or some other amount of spaces?
- How long should lines be? Traditionally was 80 columns (historical size of screens)
- Other spacing, like `if ( x == 5 )` how many of those spaces should be there?



# Coding Style – Curly Braces

- `int function() {?`
- Or should it be next line?
- Should `int` be on its own line too?



# Coding Style – Variable Names

- Function Naming Styles
  - `count_active_users()`
  - `CountActiveUsers()` (camel-case)
- Variable Naming Styles
  - `int i;`
  - `int IndexForTheFirstForLoop;`
  - `u32iLoopIndex` (Hungarian notation, include type info in name)



# indent tool

- The `indent` program can reformat your code to match the “proper” style for a project





# Coding Style – Linux kernel stuff

- Use of typedefs to make types shorter? `vpt_a` vs `struct virtual_pointer *a`
- Having only one exit to a function (using `goto`)
- Restricting the size functions can get



# How Executables are Made

- Compiler generates ASM (Cross-compiler)
- Assembler generates machine language objects
- Linker creates Executable (out of objects)



# Tools – Compiler

- takes code, usually (but not always) generates assembly
- Compiler can have front-end which generates intermediate language, which is then optimized, and back-end generates assembly
- Can be quite complex
- Examples: gcc, clang
- What language is a compiler written in? Who wrote the first one?

Thompson's *Reflections on Trusting Trust*



# Tools – Assembler

- Takes assembly language and generates machine language
- creates object files
- Relatively easy to write (mostly string parsing and bit-manipulation)
- Examples: GNU Assembler (gas), tasm, nasm, masm, etc.



# Tools – Linker

- Creates executable files from object files
- Resolves addresses of symbols.
- Links to symbols in libraries.
- Examples: ld, gold (hard to write)



# ELF Executable Format

- Binary contains your code
- Also contains initialized data
- Also a bunch of headers to tell the OS how to run things
- We'll discuss this more later



# Application Binary Interface (ABI)

- The rules an executable needs to follow in order to talk to other code/libraries on the system
- A software agreement, this is not enforced at all by hardware



# ARM32 Linux C/userspace ABI

- r0-r3 are first 4 arguments/scratch (extra go on stack) (caller saved)
- r0-r1 are return value
- r4-r11 are general purpose, callee saved
- r12-r15 are special (stack, LR, PC)
- Things are more complex than this. Passing arrays and structs? 64-bit values? Floating point values? etc.





# Kernel Programming ABIs

- OABI – “old” original ABI (arm). Being phased out. slightly different syscall mechanism, different alignment restrictions
- EABI – new “embedded” ABI (armel)
- hard float – EABI compiled with ARMv7 and VFP (vector floating point) support (armhf). Raspberry Pi (raspbian) is compiled for ARMv6 armhf.



# Linux System Calls (EABI/armhf)

- System call number in r7
- Arguments in r0 - r6
- Return value in r0 (-1 if error, errno in -4096 - 0)
- Call `swi 0x0`
- System call numbers can be found in  
`/usr/include/arm-linux-gnueabi/hf/asm/unistd.h`  
They are similar to the 32-bit x86 ones.



# How was OABI different

- The previous implementation had the same system call numbers, but instead of r7 the number was the argument to `swi`.
- This was very slow, as there is no way to determine that value without having the kernel backtrace the callstack and disassemble the instruction.



# Manpage

The easiest place to get system call documentation.

```
man open 2
```

Finds the documentation for “open”. The 2 means look for system call documentation (which is type 2).



# ARM ISAs

- ARM32
- Thumb
- Thumb2 (as seen on ECE271 ARM Cortex-M)
- AARCH64



# A first ARM assembly program: hello\_exit

```
.equ SYSCALL_EXIT,      1

        .globl _start
_start:

        #=====
        # Exit
        #=====

exit:
        mov     r0,#5
        mov     r7,#SYSCALL_EXIT      @ put exit syscall number (1) in r7
        swi     0x0                    @ and exit
```



# Some GNU assembler notes

- Code comments
  - @ is the traditional comment character
  - # can be used on line by itself but will confuse assembler if on line with code.
  - Can also use /\* \*/ and //
  - \*Cannot\* use ;
- Order is source, destination
- Constant value indicated by # or \$
- .equ is equivalent to a C #define



# hello\_exit example

Assembling/Linking using make, running, and checking the output.

```
lecture6$ make hello_exit_arm
as -o hello_exit_arm.o hello_exit_arm.s
ld -o hello_exit_arm hello_exit_arm.o
lecture6$ ./hello_exit_arm
lecture6$ echo $?
5
```





# Let's look at our executable

- `ls -la ./hello_exit_arm`  
Check the size
- `readelf -a ./hello_exit_arm`  
Look at the ELF executable layout
- `objdump --disassemble-all ./hello_exit_arm`  
See the machine code we generated
- `strace ./hello_exit_arm`  
Trace the system calls as they happen.



```
.equ SYSCALL_EXIT, 1
.equ SYSCALL_WRITE, 4
.equ STDOUT, 1
```

# hello\_world example

```
        .globl _start
_start:
        mov     r0,#STDOUT           /* stdout */
        ldr     r1,=hello
        mov     r2,#13               @ length
        mov     r7,#SYSCALL_WRITE
        swi     0x0

        # Exit
exit:
        mov     r0,#5
        mov     r7,#SYSCALL_EXIT    @ put exit syscall number in r7
        swi     0x0                 @ and exit

.data
hello:  .ascii "Hello_World!\n"
```



# New things to note in `hello_world`

- The fixed-length 32-bit ARM cannot hold a full 32-bit immediate
- Therefore a 32-bit address cannot be loaded in a single instruction
- In this case the “=” is used to request the address be stored in a “literal” pool which can be reached by PC-offset, with an extra layer of indirection.
- Data can be declared with `.ascii`, `.word`, `.byte`
- BSS can be declared with `.lcomm`



# Using gdb with hello\_world

- Run `gdb ./hello_world`
- Type *run* to run program, will exit normally
- Can set breakpoint `break exit`
- Can single-step
- Can *info regis* to see registers
- Can *disassem* to see disassembly

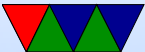


# simple loop example

```
# for(i=0;i<10;i++) do_something();
```

```
loop:  mov     r0,#0           # set loop index to zero
       push  {r0}         # save r0 on stack
       bl   do_something  # branch to subroutine, saving
                          # return address in link register
       pop  {r0}         # restore r0 from stack

       add  r0,r0,#1      # increment loop counter
       cmp  r0,#10       # have we reached 10 yet?
       bne  loop         # if not, loop
```



# string count example

Count the number of chars in a string until we hit a space.

```
    ldr    r1,=hello        # load pointer to hello string into r1
    mov    r2,#0           # initialize count to zero
loop:
    ldrb   r0,[r1]         # load byte pointed by r1 into r0
    cmp    r0,#' '        # compare r0 to space character
                                # this updates the status flags
    beq    done           # if it was equal, we are done
    add    r2,r2,#1       # increment our count
    add    r1,r1,#1       # increment our pointer
    b     loop           # branch (unconditionally) to loop
done:
```

