

ECE471: Embedded Systems – Homework 8

1-wire bus

Due: (Updated) Thursday, 12 November 2015, 9:30AM EST

1. Use your Raspberry Pi for this homework.

You will need a DS18B20 1-wire temperature probe (looks like a transistor) and pull-up resistor as handed out in class. If you missed class, you can stop by my office to pick these up.

You can view the datasheet for the DS18B20:

http://web.eece.maine.edu/~vweaver/classes/ece471_2014f/datasheets/DS18B20.pdf

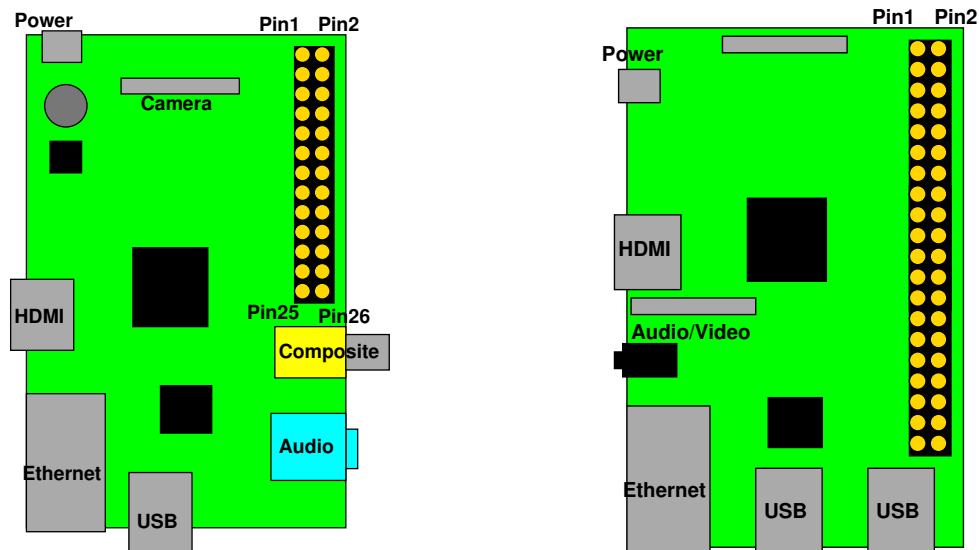


Figure 1: Location of header on Raspberry Pi Model B and 2/B+

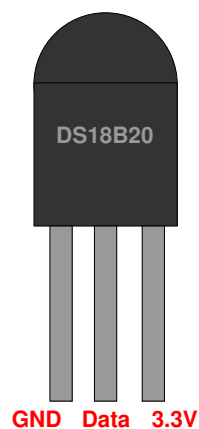


Figure 2: DS18B20 Pinout

2. **Get the DS18B20 temperature readings over 1-wire (6 points)**

First wire up the 1-wire device to the Raspberry Pi. You can use Figure 1 and Table 1 for guidance, as well as Figure 2.

Table 1: Raspberry Pi Header Pinout

3.3V	1	2	5V
GPIO2 (SDA)	3	4	5V
GPIO3 (SCL)	5	6	GND
GPIO4	7	8	GPIO14 (UART_TXD)
GND	9	10	GPIO15 (UART_RXD)
GPIO17	11	12	GPIO18 (PCM_CLK)
GPIO27	13	14	GND
GPIO22	15	16	GPIO23
3.3V	17	18	GPIO24
GPIO10 (MOSI)	19	20	GND
GPIO9 (MISO)	21	22	GPIO25
GPIO11 (SCLK)	23	24	GPIO8 (CE0)
GND	25	26	GPIO7 (CE1)
ID_SD (EEPROM)	27	28	ID_SC (EEPROM)
GPIO5	29	30	GND
GPIO6	31	32	GPIO12
GPIO13	33	34	GND
GPIO19	35	36	GPIO16
GPIO26	37	38	GPIO20
GND	39	40	GPIO21

- (a) Put the DS18B20 device on a breadboard:
 Connect 3.3V on the Pi to 3.3V on the DS18B20.
 Connect GND on the Pi to GND on the DS18B20.
 Connect GPIO4 on the Pi to Data on the DS18B20.
 Connect GPIO4 to 3.3V via the pullup resistor.
- (b) Enable 1-wire support in Linux running on your Pi. First on newer systems you will need to enable it at the firmware device-tree level.
 Edit `/boot/config.txt`, add the line `dtoverlay=w1-gpio` to the end of the file, then reboot.

Next enable the 1-wire gpio and 1-wire thermal driver:

```
sudo modprobe w1-gpio
sudo modprobe w1-therm
```

- (c) Modify the `temp_1wire.c` file to read values from the DS18B20 and print them to the screen. See the classnotes for more details.
- Find the unique-id for your DS18B20 device.
 Look for a directory under `/sys/bus/w1/devices/` that looks something like `28-000005aaf7ed`.
 - Modify the provided `read_temp()` routine so it returns the temperature in degrees C as a floating point value.

- Open `/sys/bus/w1/devices/28-000005aaf7ed/w1-slave` (replacing the unique ID with your own) for reading.
- Read the file. There are two values you want to grab, the YES value at the end of the first line and the `t=24125` value from the end of the second line. One easy way to do this is to use `fscanf()` but you can use any method that works (there are many).
To use `fscanf` of a string, do something like


```
char string1[256], string2[256];
FILE *fff;
fff=fopen("filename", "r");
fscanf(fff, "%s %s", string1, string2);
```

 HINT: If you want to read a string but not actually store the value (in effect, skipping a value from the stream) you can do something like:


```
fscanf(fff, "%*s %s", string1);
```

 The asterisk there means to read the value but not store it anywhere.
- Read the YES/NO value from the end of the first line and check if the value is YES. If it isn't, print an error and return an invalid temperature value. (HINT, you can use `strcmp()` if you want, but be careful, it works backward from what you might expect). Next, read the `t=XXXXX` value. It is in miliCelsius, so first get the value (skipping the `t=` part; there are various ways to do this, remember that in C strings are just arrays of char, and arrays are just pointers). Convert the integer miliCelsius value to floating point regular Celsius, and return.
 - In an infinite loop, read the temperature value in C and print it to the screen once a second.

(d) Be sure to comment your code!

3. Something Cool (1 point)

Copy your code to `temp_cool.c` and modify it to do something cool.

- (Easy) Print the temperature in a different unit (Fahrenheit, Kelvin)
- (Hard) Make the code also read the TMP36 sensor from last homework, and compare how closely the temperatures match.

4. Questions (2 points)

Answer the following in the README file:

- (a) One-wire in theory only uses 1-wire for data plus ground. In this lab we hooked up Vdd too. Why did we do that? (Hint, look up what's needed to use parasite power mode in the DS18B20 manual).
- (b) If you wanted to connect your pi to a temperature probe 100 yards (approximately 100 meters) away, and your choices were i2c, spi, or 1-wire, which bus would you use and why?

5. Linux Fun (1 point)

On Linux you can create shell scripts, which are simple scripts that run shell commands.

The first line contains the path to the program that you want to interpret the path. For example

```
#!/bin/sh
```

What follows are just a list of commands as you'd type at the prompt.

The "echo" command is used to print text.

```
echo "Hello World"
```

Lines starting with a hash # are comment lines.

- (a) Edit the `sample.sh` file (the provided file is empty) to use the `/bin/sh` shell, and then print a message of your choice using `echo`

Make the file executable by using the command `chmod +x sample.sh`

Be sure to add comments to your script!

Test your shell script by running `./sample.sh`

6. Submitting your work

- Run `make submit` which will create a `hw8_submit.tar.gz` file containing `Makefile`, `README`, `sample.sh`, `temp_cool.c` and `display_temp.c`. You can verify the contents with `tar -tzvf hw8_submit.tar.gz`
- e-mail the `hw8_submit.tar.gz` file to me by the homework deadline. Be sure to send the proper file!