

# ECE 471 – Embedded Systems

## Lecture 27

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14 November 2018

# Announcements

- I will respond soon to project ideas!
- Midterm Friday
- Makeup test on Thursday if you need it, contact me please
- HW grades have been posted



# Academic Integrity

- I shouldn't have to be telling this to a 400 level class
- Things that are OK
  - Writing own code
  - Writing code, sharing with partner
  - Writing code, needing help, ask me, or the TA (colin.leary)
  - Writing code, doing a google search for help (help! not looking for code to copy, but for advice)
  - Writing code, asking other students in class to look at



- it or discuss at high level the problem
- Things that are \*not\* OK
    - Taking someone else's code verbatim and turning it in as yours.
    - Cut-and-pasting major chunks of code from someone else, turning it in as yours
    - Taking someone else's code, retyping it, maybe changing the indentation, comments, and copy/replacing a few variable names and turning it in as yours
  - We learned in the last few classes why copying code



you don't really understand is bad (could read to rocket crashes, etc)

- It's also a good way to get your company sued if you get caught doing this at your job



# Homework 6 Review

- i2c: No, the clock is not fully implemented in the protocol. What does that mean? Many groups used that exact wording too.
- read\_SCL is unused. how would it be used? clock stretching
- Yes – can be used for system load but that's not really the intended purpose. Test interrupts?
- Code: be careful cutting and pasting! A lot of issues where you cut and paste SDA code to SCL but forgot



to change SDA to SCL  
Changing what GPIOs are used?



# Homework 7 Review

- Be sure to set single-ended mode properly (see data sheet)  
0xa not 0x2
- Make sure for temp you have it hooked to CH2
- How to clear all but bottom 2 bits? and with 0x3 (not 0x2)
- When doing C to F, be sure to use floating point constants 5.0/9.0 or else C does integer math.  
really, think about what temp it is





- Use the right conversion routines. The ones in class/the manual, not just something you find on the internet
- Don't memset after you set the values for the ioctl
- people with Analog Discovery



# Homework 8 Review

- Some C coding mistakes
  - Error checking. Exit if cannot open. If you don't, can segfault if try to scanf error fd
  - Returning -1 on error might be bad idea
  - Check for errors! What could go wrong? What if different sensor used, don't segfault.
  - If using streams (FILE \*fff), on fopen() error it returns NULL, not -1.
  - Be sure to close files, otherwise leak file descriptors



- Confusion about how `#define SENSOR` works. Can't include C pre-processor directives inside of a string
- `fgets` only gets up to newline
- Finding a file using C. `opendir()` `readdir()`, horrible interface
- Why need `Vdd`? To provide enough current for this particular chip needs extra current if you want parasite mode.  
You can try without `Vdd` but you will always read out 85C.  
Manual suggests MOSFET, but apparently it's possible



on Pi if use 4.7k resistor as well as “strong-pullup=y”  
kernel command line option.

- Because of distance, 1-wire
- shell script

Trouble if edit on windows, why (linefeed vs carriage  
return)

shebang description. Making executable with chmod



# Midterm Review

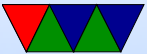
- Booting on the Pi
  - What a bootloader does
  - Why Pi is unusual
- Real Time
  - Definitions
  - Is this hard, soft, firm
- i2c/SPI/1-wire
  - Know the tradeoffs between
  - Be able to follow the C code for them



- Security
  - Buffer overrun, why it is bad
- Coding Practices
  - Be aware of the case studies we suggested
  - Know of some of the recommended ways to write safer C code



# Stuff from last time



# Good Test Practices

- Unit testing
- Test Driven Development – tests written before the code happens, needs to pass the tests before done
- Fuzzing
- Documentation  
Source control





# Space Shuttle Design

- [https://www.nasa.gov/mission\\_pages/shuttle/flyoflyfeature\\_shuttlecomputers.html](https://www.nasa.gov/mission_pages/shuttle/flyoflyfeature_shuttlecomputers.html)
- Issues normal embedded systems don't have: Vibration at liftoff, Radiation in Space
- If computer stopped for more than 120ms, shuttle could crash
- “Modern” update in 1991: 1MB Ram, 1.4MIPS. Earlier was 416k and 1/3 as fast and twice as big
- Change to code, 9 months testing in simulator, 6 months



more extensive testing

- 24 years w/o in-orbit SW problem needing patches
- 12 year stretch only 3 SW bugs found
- 400k lines of code
- HAL/S high-order assembly language (high-level language similar to PL/I)
- PASS software – runs tasks. Too big to fit in memory at once
- BFS – backup flight software. Bare minimum to takeoff, stay in orbit, safely land, fits in memory, monitors pASS during takeoff/landing Written by completely different



team.

- 28 months to develop new version
- IBM
- Extensive verification. One internal pass, one external
- 4 computers running PASS, one running BFS
- Single failure mission can continue; still land with two failures
- 4 computers in lock-step, vote, defective one kicked out

