ECE 471 – Embedded Systems Lecture 27

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Announcements

- HW#9 due Friday
- HW#5 finally turned back
 - One note, can you do int i=01101111; to get binary?
 - No, either use hex, or use 0b01101111 (gcc extension?)
 - Also, note we are using LED displays not LCD.
- \bullet I will try to have HW#7 and HW#8 graded so you can use in HW#9
 - (HW#6 might be graded last)



Hand Back and Go Over Midterms



Good Design Practices



Code Safety Standards

- Avionics: DO-178C (1992 for B)
- Industrial: IEC 61508 (1998)
- Railway: CENELEC EN 50128 (2001)
- Nuclear: IEC 61513 (2001)
- Medical: IEC 62304 (2006)
- Automotive: ISO 26262 (2011)



Automotice ISO 26262

- What is a document like this like?
- Vocab and definitions
- Management
- Safety Life Cycle
- Supporting processes
- Safety Analysis
- Risk Strategy
- Severity
 - ∘ S0 − No injuries



- S1 − No injuries
- S2 − Severe injuries
- ∘ S3 Not survivable
- Exposure
 - E0 Unlikely to Happen
 - 0 ...
 - E4 High probability
- Controllability
 - C0 Controllable
 - 0 ...
 - ∘ C3 Uncontrollable



 Look up those in a matrix so you know how to assess risk, know how important to fix, know what resources to apply



Medical Response

- IEC 62304 medical device software software lifecycle
 - Quality management system establish the requirements needed for such a device, then design methods to be sure it meets these
 - Avoid reusing software of unknown pedigree (don't just cut and paste from stackoverflow)
 - Risk management determining what all the risks involved are, then determine ways to avoid or minimize them



Software safety classification

Class A: no injury possible

Class B: Nonserious injury possible

Class C: serious injury or death possible

Software sorted into these areas. Class A do not require the same precautions as the others.



Other notes

- Top down vs Bottom up Design
 Spec out whole thing and how they work first
 Start with core part and just keep adding to it until it works
- Requirements/Specifications?



Writing Good (Embedded) C Code

- Various books. Common one: MISRA: Guidelines for the Use of the C Language in Critical Systems
- Comment your code!
- Strict, common code formatting (indentation)
- More exact variable types (int32_t not int) Size can vary on machine, and on operating system
- Subset to avoid undefined behavior



- Tool that enforces the coding standards
- Good to write safe code even if it isn't meant for a safe application. Why? Good practice. Also who knows who or when your code might be copied into another project.



More MISRA

- Motor Industry Software Reliability Association
- Guidelines: Mandatory, Required, Advisory
- Some sample guidelines
 - Avoid compiler differences int (16 or 32 bit?) int32_t
 - Avoid using functions that can fail (malloc()) allocate memory at beginning of program not throughout
 - Maintainable code, comments, coding style (see below)
- Compliance



- All mandatory rules must be met
- All required rules must have formal deviation
- Deviation
 - Must make a format explanation for why deviation is necessary
 - Prove you've thought about the issue
- MISRA 2012 has 143 rules, 16 directives
- NOTE: YOU CAN STILL WRITE BAD CODE EVEN WHEN FOLLOWING THIS

It just makes it easier to write good maintainable code.



C Style

- What can C look like?
 IOCCC (International Obfuscated C Code Competition)
- Variable style, CamelCase, under_score, Hungarian
 Notation
- Indentation (tabs vs spaces)
- Curly braces on same or next line
- Comment style
- Auto-generated documentation from comments



Good Test Practices

- Unit testing
- Test Driven Development tests written before the code happens, needs to pass the tests before done
- Fuzzing
- Device Hardening?



Good Documentation Practices

- Comment your code
- Write documentation! Make sure it matches code!
 There are some tools that can auto-generate documentation from special code comments
- Use source control (git, subversion, mercurial)
- Use good commit messages in your source control



Space Shuttle Design

- https://www.nasa.gov/mission_pages/shuttle/flyoflyfeature_shuttlecomputers.html
- Issues normal embedded systems don't have: Vibration at liftoff, Radiation in Space
- If computer stopped for more than 120ms, shuttle could crash
- "Modern" update in 1991: 1MB Ram, 1.4MIPS. Earlier was 416k and 1/3 as fast and twice as big
- Change to code, 9 months testing in simulator, 6 months



more extensive testing

- 24 years w/o in-orbit SW problem needing patches
- 12 year stretch only 3 SW bugs found
- 400k lines of code
- \bullet HAL/S high-order assembly language (high-level language similar to PL/I)
- PASS software runs tasks. Too big to fit in memory at once
- BFS backup flight software. Bare minimum to takeoff, stay in orbit, safely land, fits in memory, monitors pASS during takeoff/landing Written by completely different



team.

- 28 months to develop new version
- IBM
- Extensive verification. One internal pass, one external
- 4 computers running PASS, one running BFS
- Single failure mission can continue; still land with two failures
- 4 computers in lock-step, vote, defective one kicked out

