ECE 598 – Advanced Operating Systems Lecture 2

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Announcements

- Homework 1 will be posted tomorrow
- How is the Raspberry Pi situation?
- Need Pi, SD-card (an extra is nice if you already have Linux on one), USB-micro power for cable. Also some way to write a file to SD-card (SD card reader in laptop is fine).



Compiling your Operating System

- This varies wildly
- It can also take a very long time
- Code usually in some sort of source control



The Linux Kernel

- What language is the kernel written in?
- C and assembly mostly (with some helper shell/perl scripts)
- Why C?
 - Low-level, close to hardware (portable assembler)
 - Fast
 - Historical
 - Downsides: buggy, security bugs
- Why not C++ (or Java or Rust or Go)



- \circ Historical reasons, cost to change
- Overhead/speed (is 10-15% slower OK?)
- Higher level languages harder to predict (operator overload, exception handling, garbage collection, etc)



Linux kernel releases

- Currently 4.4
- Linus released kernel
- Spends next two weeks in "merge window" merging all the well-tested patches that have accumulated. Then releases -rc1
- Series of -rc as things are tested
- After -rc7 or -rc8 releases final version. Repeat
- Distributions or volunteers will often maintain older 'stable' versions that aren't quite as cutting edge



Building Linux Kernel by Hand

- Has anyone done this before? (Maybe in 331)
- Check out with git or download tarball:

git clone git://git.kernel.org/pub/scm/linux/kernel/git/torvalds/linux.git
http://www.kernel.org/pub/linux/kernel/v4.x/

 Configure. (complicated and verbose) make config or make menuconfig Also can copy existing .config and run make oldconfig



- Compile.
 make
 What does make -j 8 do differently?
- Make the modules.
 make modules
- sudo make modules_install
- sudo make install or manually copy bzImage to boot, update boot loader
- Cleanup, make clean and make mrproper



Building Linux Automated

- If in a distro there are other commands to building a package.
- For example on Debian make-kpkg --initrd --rootcmd fakeroot kernel_image
- Then dpkg -i to install; easier to track



Overhead (i.e. why not to do it natively on a Pi)

 Size – clean git source tree (x86) 1.8GB, compiled with kernel, 2.5GB, compiled kernel with debug features (x86), 12GB!!!

Tarball version with compiled kernel (ARM) 1.5GB

• Time to compile – minutes (on fast multicore x86 machine) to hours (18 hours or so on Pi-B+)



Linux on the Pi

- Mainline kernel, bcm2835/bcm2836 tree Missing some features
- Raspberry-pi foundation bcm2708/bcm2709 tree More complete, not upstream
- Why everything not upstream? Common problem, especially on ARM. Getting upstream is hard, high standards. Takes patience and time, small one-off ARM boards do not have the resources for the process.



Compiling – how does it work?

Traditionally this is how it works, can vary.

- compiler takes C-code (.c), makes assembly language (.s)
- assembler takes assembly (.c), makes object file (.obj) machine language
- **linker** takes object file, resolves addresses, arranges output based on *linker script*, creates executable
- Who wrote the first compiler? Assembler? Machine language?



Tools

- compiler: we use gcc, others exist (intel, microsoft, llvm/clang)
- assembler: GNU Assembler as (others: tasm, nasm, masm, etc.)
- linker: Id



Converting C to assembly

- You can use gcc -S to have it dump out the assembly it makes
- The whole process is fairly complex, you can take whole classes on it.



Converting Assembly to Machine Language

Thankfully the assembler does this for you.

ARM32 ADD instruction - $0 \ge 0303080 ==$ add r3, r0, r0, lsl #1

ADD{S}<c> <Rd>,<Rn>,<Rm>{,<shift>}

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
cond			0	0	0	0	1	0 pcod	0 e	S		R	ln		

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Rd				Shift imm5				Sh ty		Sh Reg	Rm				



Executable Format

- ELF (Executable and Linkable Format, Extensible Linking Format)
 Default for Linux and some other similar OSes header, then header table describing chunks and where they go
- Other executable formats: a.out, COFF, binary blob



ELF Layout

ELF Header

Program header

Text (Machine Code)

Data (Initialized Data)

Symbols

Debugging Info

. . . .

Section header



ELF Description

- ELF Header includes a "magic number" saying it's 0x7f,ELF, architecture type, OS type, etc. Also location of program header and section header and entry point.
- Program Header, used for execution: has info telling the OS what parts to load, how, and where (address, permission, size, alignment)
- Program Data follows, describes data actually loaded into memory: machine code, initialized data



- Other data: things like symbol names, debugging info (DWARF), etc.
 DWARF backronym = "Debugging with Attributed Record Formats"
- Section Header, used when linking: has info on the additional segments in code that aren't loaded into memory, such as debugging, symbols, etc.



Cross-compiling

- Building for a different architecture
- Why? ARM machines often slow
- Why not? Source tree has to be handle this. Makefile. etc. Usually easier to compile natively
- Linux kernel tends to cross compile OK.

