



$T_{2,d} \rightarrow R_{z,\theta} \rightarrow T_{4,a} \rightarrow R_{y,\alpha}$

	$d$	$\theta$	$a$	$\alpha$
1	0	$\theta_1 - 90$	3	-90
2	12	$\theta_2 - 90$	0	-90
3	$d_3$	180	0	0